

NAMIBIA UNIVERSITY

OF SCIENCE AND TECHNOLOGY

FACULTY OF ENGINEERING AND SPATIAL SCIENCES

DEPARTMENT OF ARCHITECURE AND SPATIAL SCIENCES

QUALIFICATION: BACHELOR OF NATURAL RESOURCE MANAGEMENT (NATURE CONSERVATION), BACHELOR OF GEOINFORMATION TECHNOLOGY, BACHELOR OF LAND ADMINISTRATION, BACHELOR OF PROPERTY STUDIES HONOURS, BACHELOR OF REGIONAL AND RURAL DEVELOPMENT, BACHELOR OF TOWN AND REGIONAL PLANNING, DIPLOMA IN PROPERTY STUDIES QUALIFICATION CODE: 07BNRS, 07BGEI, 08BPRS, 07BRAR, 07BTAR, LEVEL: 4 07BLAM, 06DPRS COURSE: **INTRODUCTION TO COURSE CODE: IGD411S GEOSPATIAL DATA** SESSION: PAPER: **JULY 2022 THEORY DURATION: 2 HOURS** MARKS: 80

SECONI	O OPPORTUNITY / SUPPLEMENTARY EXAMINATION QUESTION PAPER
EXAMINER:	MS. D. HUSSELMANN
MODERATOR:	MR E. NAOSEB

INSTRUCTIONS

- 1. Answer ALL the questions.
- 2. Write clearly and neatly.
- 3. Number the answers clearly.
- 4. Answers to calculations must be rounded off to three decimal places, excluding answers to co-ordinate conversions

PERMISSIBLE MATERIALS

- 1. Examination paper.
- 2. Examination script.
- 3. Calculators and other drawing equipment.

THIS QUESTION PAPER CONSISTS OF 5 PAGES (Including this front page)

Question 1

State whether the following is True or False.

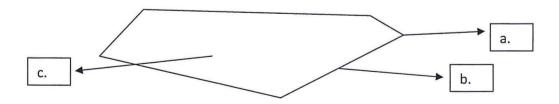
(10)

- 1.1. Lines of latitude run north to south and shows direction north and south.
- 1.2. A spatial point is defined by an exact location in space. It has no volume, area or length.
- 1.3. Geospatial data is special data that is referenced to the earth.
- 1.4. Maps are flat, but the surfaces they represent are curved.
- 1.5. Linear interpolation is used to determine the distance between two contour lines.
- 1.6. Your eyes can be considered as a remote sensor.
- 1.7. Aerial photographs are also generalised or symbolised as maps.
- 1.8. GPS stands for Geographical Positioning System
- 1.9. GPS works anywhere in the world, 24 hours a day.
- 1.10. The lower the PDOP, the more reliable the GPS position.

[10]

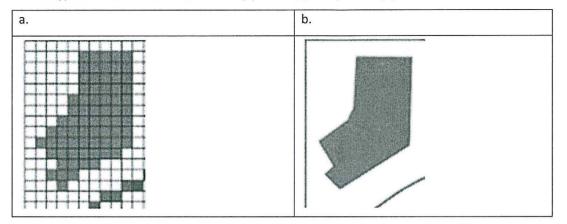
Question 2

2.1. A polygon is known to be a vector data model and can be defined as a plane figure that is bound by a closed path or circuit, composed of a finite sequence of straight-line segments. Identify the various parts of the polygon in the figure below: (3)



(2)

2.2. What type of data model is illustrated by picture (a) and picture (b)?



2.3. Differentiate between Meridians and Parallels.

(4)

2.4. Calculate the distance from 17° E to 29° E at 34.5608° S.

(4)

(1)

2.5. What is the result of referencing geodetic coordinates to the wrong datum?

[14]

Question 3

3.1. Calculate the spherical distance from A to C.

(10)

- A 22.8765° S
- 16.8596° E
- C 22.0356° S
- 14.2143° E
- 3.2. Convert 46°38′29" S to Decimal Degrees. Show your work.

(2)

3.3. Convert 78,1943° to Degrees Minutes and Seconds. Show your work.

(2) [**14**]

Question 4

4.1 Why is the title of a map important?

(1)

4.2 What is a contour interval?

(1)

Introd	uction to Geospatial Data			IGD411S		
4.3	List the six activities that constitute the map generalisation process.					
4.4	Given the following co-ordinate	es:				
	Υ	Х	Z			
Α	-7 809.68	+60 475.25	1665.77			
В	-7 884.32	+60 511.49	1650.51			
a. Calculate the slope in degrees from point A to B. (
b. Convert your slope degrees to percentage.						
				[12]		
	- Const	Control of the Contro				
Question 5						
5.1	What is Aerial Photography?					
5.2	Name two characteristics of ae	(2)				
5.3	List all the (a) advantages and ((5)				
5.4	Aerial photographs are useful for providing spatial information, but they usually contain geome					
	distortions. Name three types	of displacements that cause	geometric distortion.	(3)		
5.5	Calculate the size of the area covered by a photograph measuring 18 cm by 9 cm on a scale of					
	1:7000. Give your answer in he	ectares.		(6)		
				[18]		
	· · · · · · · · · · · · · · · · · · ·					
Ques	tion 6					
6.1	Name and differentiate between two types of GPS positioning modes. State which one is more accurate right next to its name.					
6.2	List the 4 types of dilution of precision (DOP). Write them out in full words and not abbreviations. (4					

IGD411S

- 6.3 The number of satellites is tracked by two different receivers; receiver A and receiver B. Name the receiver that will result in the most accurate position if receiver A tracks 4 satellites and receiver B tracks 8 satellites. (1)
- 6.4 What does SV stand for? (1)
- 6.5 What is the minimum number of satellites required to compute a reliable GPS position? (1)

[12]